



On a coupled system of Urysohn-Stieltjes integral equations in reflexive Banach space

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Abstract

Urysohn-Stieltjes integral operators and Urysohn-Stieltjes integral equations have been studied by some authors. In this paper we prove the existence of at least one weak solution of a coupled system of Urysohn-Stieltjes integral equations in the reflexive Banach space. We used the O'Regan fixed point theorem and some propositions. As an application, the coupled system of Hammerstien-Stieltjes integral equations is also studied.

Keywords: Weak solution, weakly Riemann-Stieltjes integral, coupled system, weakly relatively compact.

1 Introduction and preliminaries

The Volterra-Stieltjes integral equations and Urysohn-Stieltjes integral equations have been studied by J. Banaś and some other authors (see [1]-[9] and [18]- [20]).

Consider the Urysohn-Stieltjes integral equation

$$x(t) = p(t) + \int_0^1 f(t, s, x(s)) d_s g(t, s), \quad t \in I = [0, 1]. \quad (1)$$

J. Banaś (see [5]) proved the existence of at least one solution $x \in C(I)$ to the equation (1), where $g : I \times I \rightarrow R$ is nondecreasing in the second argument on I and the symbol d_s indicates the integration with respect to s .

For the definition, background and properties of the Stieltjes integral we refer to Banaś [1]. However, the coupled system of integral equations have been studied, recently, by some authors (see [13]-[14],[16]).

In this paper, we generalize this results to study the existence of weak solutions $(x, y) \in C[I, E] \times C[I, E]$ for the coupled system of Urysohn-Stieltjes integral equations

$$x(t) = a_1(t) + \int_0^1 f_1(t, s, y(s)) d_s g_1(t, s), \quad t \in I \quad (2)$$

$$y(t) = a_2(t) + \int_0^1 f_2(t, s, x(s)) d_s g_2(t, s), \quad t \in I$$

in reflexive Banach space E under the weak-weak continuity assumption imposed on $f_i : I \times I \times E \rightarrow E$, $i = 1, 2$.

As an application, we study the existence of weak solutions $x, y \in C[I, E]$ for the coupled system of Hammerstien-Stieltjes integral equations

$$x(t) = a_1(t) + \int_0^1 k_1(t, s) h_1(s, y(s)) d_s g_1(t, s), \quad t \in I \quad (3)$$

$$y(t) = a_2(t) + \int_0^1 k_2(t, s) h_2(s, x(s)) d_s g_2(t, s), \quad t \in I$$

Throughout this paper, if otherwise is not stated, E denotes a reflexive Banach space with norm $\| \cdot \|$ and dual E^* . Denote by $C[I, E]$ the Banach space of strongly continuous functions $x : I \rightarrow E$ with sup-norm. Let

$X = C[I, E] \times C[I, E] = \{u(t) = (x(t), y(t)) : x \in C[I, E], y \in C[I, E], t \in I\}$ be a Banach space with the norm defined as

$$\| (x, y) \|_X = \max\{\| x \|_{C[I, E]} + \| y \|_{C[I, E]}\}, \quad \forall (x, y) \in X.$$

Now, we shall present some auxiliary results that will be needed in this work. Let E be a Banach space (need not be reflexive) and let $x : [a, b] \rightarrow E$, then

- (1-) $x(\cdot)$ is said to be weakly continuous (measurable) at $t_0 \in [a, b]$ if for every $\phi \in E^*$, $\phi(x(\cdot))$ is continuous (measurable) at t_0 .
- (2-) A function $h : E \rightarrow E$ is said to be weakly sequentially continuous if h maps weakly convergent sequences in E to weakly convergent sequences in E .

If x is weakly continuous on I , then x is strongly measurable and hence weakly measurable (see [17] and [11]). It is evident that in reflexive Banach spaces, if x is weakly continuous function on $[a, b]$, then x is weakly Riemann integrable (see [17]). Since the space of all weakly Riemann-Stieltjes integrable functions is not complete, we will restrict our attention to the existence of weak solutions of the coupled system (2) in the space $C[I, E] \times C[I, E]$.

Definition 1 Let $f : I \times E \rightarrow E$. Then $f(t, u)$ is said to be weakly-weakly continuous at (t_0, u_0) if given $\epsilon > 0$, $\phi \in E^*$ there exists $\delta > 0$ and a weakly open set U containing u_0 such that

$$|\phi(f(t, u) - f(t_0, u_0))| < \epsilon$$

whenever

$$|t - t_0| < \delta \text{ and } u \in U.$$

Now, we have the following fixed point theorem, due to O'Regan, in the reflexive Banach space (see [21]) and some propositions which will be used in the sequel (see [12]).

Theorem 1 Let E be a Banach space and let Q be a nonempty, bounded, closed and convex subset of $C[I, E]$ and let $F : Q \rightarrow Q$ be a weakly sequentially continuous and assume that $FQ(t)$ is relatively weakly compact in E for each $t \in I$. Then, F has a fixed point in the set Q .

Proposition 1 In reflexive Banach space, the subset is weakly relatively compact if and only if it is bounded in the norm topology.

Proposition 2 Let E be a normed space with $y \in E$ and $y \neq 0$. Then there exists a $\varphi \in E^*$ with $\|\varphi\| = 1$ and $\|y\| = \varphi(y)$.

2 Main results

In this section, we present our main result by proving the existence of weak solutions for the coupled system of Urysohn-Stieltjes integral equations (2) in the reflexive Banach space E . Let us first state the following assumptions:

- (i) $a_i \in C[I, E]$, $i = 1, 2$.
- (ii) $f_i : I \times I \times D \rightarrow E$, where $D \subset E$ and $i = 1, 2$ satisfy the following conditions:
 - (1) $f_i(\cdot, s, x(s))$ is continuous function, $\forall s \in I, x \in D \subset E$.
 - (2) $f_i(t, \cdot, \cdot)$ is weakly-weakly continuous function, $\forall t \in I$.
 - (3) The weak closure of the range of $f_i(I \times I \times D)$ are weakly compact in E (or equivalently: there exists a constant M such that $\| f_i(t, s, x) \| \leq M$).
- (iii) The functions $g_i : I \times I \rightarrow R$ and the functions $t \rightarrow g_i(t, 1)$ and $t \rightarrow g_i(t, 0)$ ($i = 1, 2$) are continuous on I , and $\mu = \max\{\sup | g_i(t, 1) | + \sup | g_i(t, 0) | \text{ on } I\}$.
- (iv) For all $t_1, t_2 \in I$ such that $t_1 < t_2$ the functions $s \rightarrow g_i(t_2, s) - g_i(t_1, s)$ are nondecreasing on I .
- (v) $g_i(0, s) = 0$ for any $s \in I$.

Remark 1. Observe that assumptions (iv) and (v) imply that the function $s \rightarrow g(t, s)$ is nondecreasing on the interval I , for any fixed $t \in I$ (Remark 1 in [6]). Indeed, putting $t_2 = t$, $t_1 = 0$ in (iv) and keeping in mind (v), we obtain the desired conclusion. From this observation, it follows immediately that, for every $t \in I$, the function $s \rightarrow g(t, s)$ is of bounded variation on I .

Definition 2 By a weak solution for the coupled system (2), we mean the pair of functions $(x, y) \in C[I, E] \times C[I, E]$ such that

$$\varphi(x(t)) = \varphi(a_1(t)) + \int_0^1 \varphi(f_1(t, s, y(s))) d_s g_1(t, s), \quad t \in I$$

$$\varphi(y(t)) = \varphi(a_2(t)) + \int_0^1 \varphi(f_2(t, s, x(s))) d_s g_2(t, s), \quad t \in I$$

for all $\varphi \in E^*$.

Theorem 2 Under assumptions (i)-(v), the coupled system of Urysohn-Stieltjes integral equation (2) has at least one weak solution $(x, y) \in C[I, E] \times C[I, E]$.

Proof. Define an operator A by

$$A(x, y) = (A_1y, A_2y)$$

where

$$A_1y(t) = a_1(t) + \int_0^1 f_1(t, s, y(s)) d_s g_1(t, s), \quad t \in I$$

$$A_2x(t) = a_2(t) + \int_0^1 f_2(t, s, x(s)) d_s g_2(t, s), \quad t \in I$$

For every $x_i \in C[I, E]$, $f_i(\cdot, s, x(s))$ is continuous on I , and $f_i(t, \cdot, x(\cdot))$ are weakly continuous on I , then $\varphi(f_i(t, \cdot, x(\cdot)))$ are continuous for every $\varphi \in E^*$. Hence, in view of bounded variational of g_i it follows, $f_i(t, s, x(s))$ is weakly Riemann-Stieltjes integrable on I with respect to $s \rightarrow g_i(t, s)$. Thus A_i make sense.

Define the sets Q_1 and Q_2 by

$$Q_1 = \{y \in C[I, E] : \|y\| \leq H_1\}, \quad H_1 = \|a_1\| + M\mu,$$

And

$$Q_2 = \{x \in C[I, E] : \|x\| \leq H_2\}, \quad H_2 = \|a_2\| + M\mu.$$

Now, define the set Q by

$$Q = \{u = (x, y) \in X : \|u\| \leq H_1 + H_2\}$$

Next, let $y \in Q_1$ and $x \in Q_2$. Without loss of generality we may assume that $A_1y \neq 0, A_2x(t) \neq 0, t \in I$. By proposition 2, we have

$$\begin{aligned} \|A_1y(t)\| &= \varphi(A_1y(t)) \\ &\leq |\varphi(a_1(t))| + \left| \varphi\left(\int_0^1 f_1(t, s, y(s)) d_s g_1(t, s)\right) \right| \\ &\leq \|a_1\| + \int_0^1 |\varphi(f_1(t, s, y(s)))| d_s \left(\bigvee_{z=0}^s g_1(t, z)\right) \\ &\leq \|a_1\| + \int_0^1 \|f_1(t, s, y(s))\| d_s \left(\bigvee_{z=0}^s g_1(t, z)\right) \end{aligned}$$

$$\begin{aligned}
 &\leq \| a_1 \| + M \int_0^1 d_s g(t, s) \\
 &\leq \| a_1 \| + M [g(t, 1) - g(t, 0)] \\
 &\leq \| a_1 \| + M [\sup_{t \in I} | g(t, 1) | + \sup_{t \in I} | g(t, 0) |] \\
 &\leq \| a_1 \| + M \mu
 \end{aligned}$$

Then

$$\| A_1 y(t) \| \leq \| a_1 \| + M \mu = H_1$$

Similarly we can prove that

$$\| A_2 x(t) \| \leq \| a_2 \| + M \mu = H_2.$$

Therefore, for any $u \in Q$

$$\begin{aligned}
 \| Au(t) \| &= \| A(x, y)(t) \| = \| (A_1 y(t), A_2 x(t)) \| \\
 &\leq \| A_1 y(t) \| + \| A_2 x(t) \| \\
 &\leq \| a_1 \| + M \mu + \| a_2 \| + M \mu = H_1 + H_2.
 \end{aligned}$$

i.e., $\forall u \in Q \Rightarrow Au \in Q \Rightarrow AQ \subset Q$. Thus $A : Q \rightarrow Q$.

Also, we can prove that $A_1 : C[I, E] \rightarrow C[I, E]$ and for $t_1, t_2 \in I$, $t_1 < t_2$ (without loss of generality, we may assume that $Ax(t_2) - Ax(t_1) \neq 0$) and there exists $\varphi \in E^*$, such that

$$\begin{aligned}
 \| A_1 y(t_2) - A_1 y(t_1) \| &\leq \varphi(A_1 y(t_2) - A_1 y(t_1)) \\
 &\leq | \varphi(a_1(t_2) - a_1(t_1)) | + \left| \int_0^1 \varphi(f_1(t_2, s, y(s))) d_s g_1(t_2, s) \right. \\
 &\quad \left. - \int_0^1 \varphi(f_1(t_1, s, y(s))) d_s g_1(t_1, s) \right| \\
 &\leq \| a_1(t_2) - a_1(t_1) \| + \left| \int_0^1 \varphi(f_1(t_2, s, y(s))) d_s g_1(t_2, s) \right. \\
 &\quad \left. - \int_0^1 \varphi(f_1(t_1, s, y(s))) d_s g_1(t_2, s) \right| + \left| \int_0^1 \varphi(f_1(t_1, s, y(s))) d_s g_1(t_2, s) \right. \\
 &\quad \left. - \int_0^1 \varphi(f_1(t_1, s, y(s))) d_s g_1(t_1, s) \right| \\
 &\leq \| a_1(t_2) - a_1(t_1) \|
 \end{aligned}$$

$$\begin{aligned}
 & + \int_0^1 |\varphi(f_1(t_2, s, y(s)) - f_1(t_1, s, y(s)))| d_s \left(\bigvee_{z=0}^s g_1(t_2, z) \right) \\
 & + \int_0^1 |\varphi(f_1(t_1, s, y(s)))| d_s \left(\bigvee_{z=0}^s [g_1(t_2, z) - g_1(t_1, z)] \right) \\
 & \leq \| a_1(t_2) - a_1(t_1) \| + \| f_1(t_2, s, y(s)) - f_1(t_1, s, y(s)) \| \int_0^1 d_s g_1(t_2, s) \\
 & + \int_0^1 \| f_1(t_1, s, y(s)) \| d_s [g_1(t_2, s) - g_1(t_1, s)] \\
 & \leq \| a_1(t_2) - a_1(t_1) \| \\
 & + \| f_1(t_2, s, y(s)) - f_1(t_1, s, y(s)) \| [g_1(t_2, 1) - g_1(t_2, 0)] \\
 & + M[(g_1(t_2, 1) - g_1(t_1, 0)) - (g_1(t_2, 0) - g_1(t_1, 0))] \\
 & \leq \| a_1(t_2) - a_1(t_1) \| \\
 & + \| f_1(t_2, s, y(s)) - f_1(t_1, s, y(s)) \| [g_1(t_2, 1) - g_1(t_2, 0)] \\
 & + M[|g_1(t_2, 1) - g_1(t_1, 0)| + |g_1(t_2, 0) - g_1(t_1, 0)|]
 \end{aligned}$$

Similarly we can show that

$$\begin{aligned}
 \| A_2 x(t_2) - A_2 x(t_1) \| & \leq \| a_2(t_2) - a_2(t_1) \| \\
 & + \| f_2(t_2, s, x(s)) - f_2(t_1, s, x(s)) \| [g_2(t_2, 1) - g_2(t_2, 0)] \\
 & + M[|g_2(t_2, 1) - g_2(t_1, 0)| + |g_2(t_2, 0) - g_2(t_1, 0)|]
 \end{aligned}$$

Now, we obtain

$$\begin{aligned}
 A(x, y)(t_2) - A(x, y)(t_1) & = (A_1 y(t_2), A_2 x(t_2)) - (A_1 y(t_1), A_2 x(t_1)) \\
 & = ((A_1 y(t_2) - A_1 y(t_1)), (A_2 x(t_2) - A_2 x(t_1)))
 \end{aligned}$$

and

$$\begin{aligned}
 \| A(x, y)(t_2) - A(x, y)(t_1) \| & \leq \| A_1 y(t_2) - A_1 y(t_1) \| + \| A_2 x(t_2) - A_2 x(t_1) \| \\
 & \leq \| a_1(t_2) - a_1(t_1) \| \\
 & + \| f_1(t_2, s, y(s)) - f_1(t_1, s, y(s)) \| [g_1(t_2, 1) - g_1(t_2, 0)] \\
 & + M[|g_1(t_2, 1) - g_1(t_1, 0)| + |g_1(t_2, 0) - g_1(t_1, 0)|] \\
 & \leq \| a_2(t_2) - a_2(t_1) \| \\
 & + \| f_2(t_2, s, x(s)) - f_2(t_1, s, x(s)) \| [g_2(t_2, 1) - g_2(t_2, 0)] \\
 & + M[|g_2(t_2, 1) - g_2(t_1, 0)| + |g_2(t_2, 0) - g_2(t_1, 0)|]
 \end{aligned}$$

Note that Q is nonempty, uniformly bounded and strongly equi-continuous subset of X , by the uniform boundedness of AQ . Thus, according to propositions

1, AQ is relatively weakly compact.

It remains to prove that A is weakly sequentially continuous.

Let $\{y_n(t)\}$ and $\{x_n(t)\}$ be sequence in $C[I, E]$ weakly convergent to $y(t)$ and $x(t)$ respectively ($\forall t \in I$), since $f_1(t, s, \cdot)$ and $f_2(t, s, \cdot)$ are weakly continuous. Then $f_1(t, s, y_n(s))$ and $f_2(t, s, x_n(s))$ converge weakly to $f_1(t, s, y(s))$ and $f_2(t, s, x(s))$ respectively. Furthermore, ($\forall \varphi \in E^*$) $\varphi(f_1(t, s, y_n(s)))$ and $\varphi(f_2(t, s, x_n(s)))$ converge strongly to $\varphi(f_1(t, s, y(s)))$ and $\varphi(f_2(t, s, x(s)))$ respectively. Using assumption (3) and applying Lebesgue dominated convergence theorem, we get

$$\begin{aligned} \varphi\left(\int_0^1 f_1(t, s, y_n(s)) d_s g_1(t, s)\right) &= \int_0^1 \varphi(f_1(t, s, y_n(s))) d_s g_1(t, s) \\ &\rightarrow \int_0^1 \varphi(f_1(t, s, y(s))) d_s g_1(t, s), \quad \forall \varphi \in E^*, t \in I. \end{aligned}$$

Moreover, we have

$$\begin{aligned} \varphi\left(\int_0^1 f_2(t, s, x_n(s)) d_s g_2(t, s)\right) &= \int_0^1 \varphi(f_2(t, s, x_n(s))) d_s g_2(t, s) \\ &\rightarrow \int_0^1 \varphi(f_2(t, s, x(s))) d_s g_2(t, s), \quad \forall \varphi \in E^*, t \in I. \end{aligned}$$

Thus, A is weakly sequentially continuous on Q .

Since all conditions of Theorem 1 are satisfied, then the operator A has at least one fixed point $(x, y) = u \in Q$ and the coupled system of Urysohn-Stieltjes integral equations (2) has at least one weak solution. ■

3 Hammerstien-Stieltjes coupled system

This section, as an application, deals with the existence of weak continuous solution for the coupled system of Hammerstien-Stieltjes integral equations (3), consider the following the assumption:

(ii)* Let $h_i : I \times E \rightarrow E$ and $k_i : I \times I \rightarrow R_+$ are such that h_i, k_i satisfy the following assumptions:

(1)* $h_i(s, x(s))$ are weakly-weakly continuous functions.

(2)* There exists a constant M such that $\|h_i(s, x)\| \leq M$.

(3)* $k_i(t, s)$ is continuous function such that $K = \sup_t |k_i(t, s)|$, where K is positive constant.

Definition 3 By a weak solution for the coupled system (3), we mean the pair of functions $(x, y) \in C[I, E] \times C[I, E]$ such that

$$\varphi(x(t)) = \varphi(a_1(t)) + \int_0^1 k_1(t, s) \varphi(h_1(s, y(s))) d_s g_1(t, s), \quad t \in I$$

$$\varphi(y(t)) = \varphi(a_2(t)) + \int_0^1 k_2(t, s) \varphi(h_2(s, x(s))) d_s g_2(t, s), \quad t \in I$$

for all $\varphi \in E^*$.

Now, to prove the existence of a weak solutions of (3), we have the following theorem

Theorem 3 Let the assumptions (i), (iii)-(v) and (ii)* be satisfied. Then the coupled system of Hammerstien-Stieltjes integral equations (3) has at least one weak solution $(x, y) \in X$.

Proof. Let

$$f_i(t, s, x(s)) = k_i(t, s) h_i(s, x(s)).$$

Then from the assumption (ii)*, we find that the assumptions of Theorem 2 are satisfied and result follows.

Example : Consider the functions $g_i : I \times I \rightarrow R$ defined by the formula

$$g_1(t, s) = \begin{cases} t \ln \frac{t+s}{t}, & \text{for } t \in (0, 1], \quad s \in I, \\ 0, & \text{for } t = 0, \quad s \in I. \end{cases}$$

$$g_2(t, s) = t(t + s - 1), \quad t \in I.$$

It can be easily seen that the functions $g_1(t, s)$ and $g_2(t, s)$ satisfy assumptions (iii)-(v) given in Theorem 2. In this case, the coupled system of Urysohn-

Stieltjes integral equations (2) has the form

$$x(t) = a_1(t) + \int_0^1 \frac{t}{t+s} f_1(t, s, y(s)) ds, \quad t \in I$$

$$y(t) = a_2(t) + \int_0^1 t f_2(t, s, x(s)) ds, \quad t \in I$$
(4)

Therefore, the coupled system (4) has at least one weak solution $u = (x, y) \in X$.

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